

Variations of Solar Radius: Observations with RHESSI

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The Solar Aspect System (SAS) of the rotating (at 15 rpm) RHESSI spacecraft has three subsystems. Each of these measures the position of the limb by sampling the full solar chord profile with a linear CCD using a narrow-band filter at 670 nm. With a CCD pixel size of 1.7 arcsec, the accuracy of each of the 6 limb positions is theoretically better than 50 mas using 4 pixels at each limb. Since the launch of RHESSI early 2002, solar limbs have been sampled with at least 100 Hz. The database currently exceeds 4×10^9 individual radius measurements. The main function of SAS is to determine the RHESSI pointing relative to Sun center. The observed precision of this determination has a typical instantaneous (16 Hz) value of the order of 50 mas (rms). As a byproduct of this we observe the solar oblateness and see signatures of magnetic activity (spots and faculae). We present these first RHESSI results here.

The SAS Instrument

3 independent subsystems on rotating S/C Design

 Optics f/40 coated lens

670 nm (12 nm FWHM) bandpass filter 1550 mm focal length

three linear CCDs with 2048 pixels

length: 13 µm/pixel, total 26mm width: 13 μm/pixel

integration: programmable, typical 700 μ sec resolution: 10 bit @ 128 Hz

 Sun Image 14.4 mm

Sensor

single CCD: 59 arcmir · Field of View

high resolution: 27 arcmin

 Resolution 1.73 arcsec/pixel 0.133 arcsec/μm

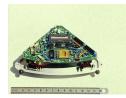
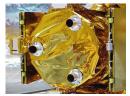


Image of one of the three SAS sensors with the front-end electronics. The cover with the integrated blocking

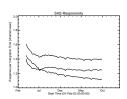


The image of the sunny side of the integrated spacecraft shows the three baffles for the

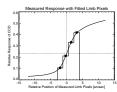
The drawing on the left shows a sketch of the SAS geometry. I ne drawing on the left shows a sketch of the SAS geometry. The three lenses focus the solar disc at 670 nm onto the three linear CCDs. Knowing the effective geometry and relating the three subsystems correctly leads to the indicated reconstruction of the sun center. Any deviation from the correct geometry leads to an ambigious reconstruction and therefore a non-vanishing

to an amongous reconstruction and therefore a non-vanishing reduced trianglemeters defining the relative geometry of all SAS feature can be fitted using the enomous statistics of measured Sun limb crossings. A set of wrong parameters leads to an in-consistent reconstruction of the Sun center.

The Calibration



Frequent readouts of the full solar profile allows a precise measurement of the responsivity.



The PSF of the three subsystems has not been measured prior to flight. Therefore it has to be estimated analysing the data. The main contribution to the width of the core is the diffraction at the lens and chromatic abberation. The estimated value prior to flight is 4.3 arcsec (FW HM). Averaging over serveral 10'000 of profile measurements results in a well sampled limb profile function. This measured limb profile contains the physical solar limb darkening a t670 nm convoluted with the instrumental response.

In first order, the solar profile at 670 nm can approximated with a step function. Therefore, the derivative of the measured and normalized limb profile gives a rough estimate of the core of the PSF. The measured width of 4.5 arcsec (FWHM) confirms the integrated measured profile.

In order to measure the side lopes of the PSF, the measured profiles have to be de-convoluted using a model for the limb darkening function.

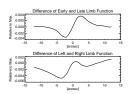
The responsivity for each of the three SAS sub-In eresponsivity for each of the three SAS sun-systems is measured in channels per µsec. The overall decrease of responsivity is caused by de-grading of the lenses. Whereas two of the three subsystems are stabelized over time, one lens still continues to degrade. This remaining degrading doesn't compromize the data since the integration time can be adjusted in order to use the full reso-lution of the data.

lution of the data.

The smaller changes in responsivity, on the time scale of weeks, is correlated with the varying duration of exposure to sun light and a subsequent small variation of the temperature of the sensor.

For every integration time, the four triggered pixels at each of the measured solar limb are fitted to the corresponding measured (averaged) limb profile function. The statistics of the data shows that the determination of the solar limb has an rms error of approximately 50 mas.

Therefore, for every cycle (16 Hz) 6 radiic an be calculated. This forms an enormous database of relatively high precision solar radii measurements.

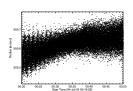


The measured limb profile function differs for the three subsystems. Moreoever, it varies in time and

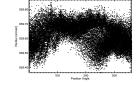
space. The upper plot shows the difference between an The upper plot shows the difference between an averaged limb profile for a time range early in the mission and an equivalent limb profile later in the mission. This difference suggests clearly that the limb profile laters over time, which means that the width of the PSF increases in time. Wiggles (e.g. at 10 arcsec) indicate information about the side lobes of the PSF.

The lower plot shows the difference between averaged limb profiles at two opposite off-axis angles and therefore the PSF, depends significantly on the off-axis angle. Therefore, come affects of the lens can and have to be quantified.

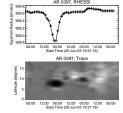
Status of Data Analysis



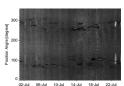
Individual points plotted as a function of time for the same orbit. This gives a feeling for the large number of measures available, and the distribution of points indicates the presence of systematic error



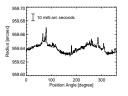
Individual radius measurements plotted as a func-tion of the heliographic position angle. The rich structure seems to carry information about dis-crapencies in the calibration.



East limb passage of NOAA active region 0397, observed at 2003 June 26, 0:30 UT. The map (bottom) shows limb latitudes from the equator to NO8. And the line plot (top) corresponds to NO8. The time resolution of the data is one RHESSI orbit or 96 min. The data essentially show excess brightness as apparent radius; there is plage and another smaller sunspot from AR 0399 following the appearance the the larger sunspot; the two spot groups had areas of 850 and 30 millionths on July 1. In future analysis we hope to distinguish photometric effects from true radius values.



Synoptic view of limb shape data for the first half of July, 2003, with solar position angle 180 degree (South) at the middle. The image is negative (faculae appear dark) and covers an range of about 2 arcsec effective radius. The faculae and sunspots appear in the active latitudes and are brightness



Plot showing a 50-orbit sum from the data in Figure to the left. A modulation consistent with the solar oblateness can readily be seen, along with excesses due mainly to facular brightness. There are also artifacts present as well as noise at a level of about 2 mas (RMS) in the 1 degree bins

Conclusion Outlook

At this point we have completed most of the work on sensor calibration and are in the process of tweaking it to suppress systematic terms of many kinds. The data shown above establish that these terms will be controllable at the level of milli-arcsec. We hope to apply these data to many purposes, especially helioseismology and the observation of solar shape variations with position and time.