

DRAFT

Imager Test Plan HSI-MI&T-IMGR-TP

> Sept. 12, 2000 Alex Zehnder

1 Introduction

1.1 Purpose

The following paper describes the test plan in order to validate the imager with its aspect data processors for flight

2 Test Plan (TBD)

2.1 System Tests (Imager Susceptibility).

Test	PF used
Prove that the RAS measures stars while all	V6s0r0ES_001 using RAS GSE
other spacecraft systems are operational.	
Prove that the SAS will measure the Sun	Needs simulators with new proms. Test
position while all other spacecraft systems	will be done at PSI using SSL IDPU
are operational.	

2.2 System Tests (Imager Radiated).

Test	PF used
Prove that the worst case noise from the SAS and RAS does not upset	V6s0r0_002 (high rate image mode)
measurements of any of the other	
spacecraft systems.	

2.3 Orbit Simulations

Test	PF used
Test that the RAS and SAS are compatible	TBD
with the Launch and Early Orbit command	
opportunities.	
Test the RAS and SAS normal orbit	
cycling data volume and commanding	
requirements.	

2.4 EMI Susceptibility

Test	PF used
Prove that the RAS and SAS perform the	V6s0r0_001 (low rate if spectrometer on)
same as before the 20V/m field exposure	V6s3r6_001 (offset levels)
(LV and Ground Radars).	

2.5 Vibration and Transportation

Test	PF used
Prove that the RAS and SAS perform the	V6s0r0_001 (low rate dark level)
same as before the vibration or	V6s3r6_001 (offset levels)

transportation.	V6s4r4_001 (internal LED)
	V6s0r0ES_001 RAS/SAS event generation
	RAS GSE needed

2.6 Thermal Vacuum Conditions

Test	PF used
Prove that the RAS/SAS measures stars while all other spacecraft systems are operational and while hot and cold.	V6s0r0_001 (low rate dark level) V6s3r6_001 (offset levels) V6s0r0ES_001 RAS/SAS event generation RAS GSE needed
Prove that the SAS will measure the sun position while all other spacecraft systems are operational and while hot and cold.	Needs simulators with new PROMS. Test will be done at PSI using IDPU

2.7 PreLaunch Conditions

Test	PF used
5	V6s0r0_001 (low rate dark level)
flight while connected to the LV and under	V6s3r6_001 (offset levels)
the plane, etc.	V6s4r4_001 (internal LED)