

On the Photometric Accuracy of RHESSI Imaging and Spectroscopy

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Abstract. We compare the photometric accuracy of spectra and images in flares observed with the *Ramaty High Energy Solar Spectroscopic Imager (RHESSI)* spacecraft. We test the accuracy of the photometry by comparing the photon fluxes obtained in different energy ranges from the spectral-fitting software SPEX with those fluxes contained in the images reconstructed with the *Clean*, *MEM*, *MEM-Vis*, *Pixon*, and *Forward-fit* algorithms. We quantify also the background fluxes, the fidelity of source geometries, and spatial spectra reconstructed with the five image reconstruction algorithms. We investigate the effects of grid selection, pixel size, field-of-view, and time intervals on the quality of image reconstruction. The detailed parameters and statistics are provided in an accompanying CD-ROM and web page. We find that *Forward-fit*, *Pixon*, and *Clean* have a robust convergence behavior and a photometric accuracy in the order of a few percents, while *MEM* does not converge optimally for large degrees of freedom (for large field-of-views and/or small pixel sizes), and *MEM-Vis* suffers in the case of time-variable sources. This comparative study documents the current status of the *RHESSI* spectral and imaging software, one year after launch.

Keywords: Sun : flares — Sun : hard X-rays

1. INTRODUCTION

The *Reuven Ramaty High Energy Solar Spectroscopic Imager (RHESSI)* was launched on 2002 Feb 5 and operated successfully through the first year, recording a total of ≈ 7500 solar flares. At this time, after one year of the mission, most of the software has matured to be both reliable and accurate, and instrumental parameters have been improved from in-flight data. Thus, it is timely to conduct a quantitative comparison



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of the performance of the various available imaging algorithms, to compare the spatial and spectral features in the reconstructed images, and to cross-calibrate the photon fluxes extracted from images against those from the (non-imaging) spectral fitting software. Such a quantitative comparison will also be useful to provide estimates of uncertainties and systematic errors in spectral fitting and spectral inversions, as well as to serve as a reference for monitoring future changes in the instrumental parameters and software developments. All image reconstructions are performed here with the software version available in March 2003.

The *RHESSI* spacecraft and its mission are described in the overview article of Lin et al. (2002), the *RHESSI* spectrometer in Smith et al. (2002), and the *RHESSI* imaging concepts in Hurford et al. (2002). Further technical articles that may be of interest in the context of this study are on *RHESSI* data analysis software (Schwartz et al. 2002), on reconstruction of *RHESSI* images with forward-fitting (Aschwanden et al. 2002a), and on pixon image reconstruction (Metcalf et al. 1996). We choose for this comparative study as main event the flare of 2002 Feb 20, 11:06 UT, because this event was already subject of various analyses in a number of previous publications (Krucker & Lin 2002, Sui et al. 2002, Vilmer et al. 2002, Brown et al. 2002, Aschwanden et al. 2002b, Kontar et al. 2002), as well as the two additional flares of 2002 May 18, 19:15 UT, and 2002 Jul 23, 00:30 UT.

2. RESULTS OF DATA ANALYSIS

The details of the data analysis are provided on the accompanying CD-ROM (or on the web-page http://www.lmsal.com/~aschwand/eprints/2003_photo/index.html). Here we summarize only the main results of this analysis, which includes a detailed parametric study of the 2002 Feb 20 flare (§A1-A11 on CD-ROM), as well as additional tests on flares with different source morphologies and flare positions, i.e., the single-source flare from 2002 May 18 (§B1 on CD-ROM) and the complex-source X-ray flare of 2002 Jul 23 (§C1 on CD-ROM).

2.1. SPECTRAL PHOTOMETRY (§A1 ON CD-ROM)

The photometry can be obtained from two different software codes in the *RHESSI SolarSoftWare (SSW)*, either from the spectral fitting package *SPEX* (Schwartz et al. 2002; Smith et al. 2002), or from the *RHESSI* image reconstruction algorithms. Both codes use the same input in form of time-tagged photon event lists, but the *RHESSI* response function is applied in a different manner to obtain photon counts in a

Table I. Ratios of image-integrated photon fluxes to the total spectral fluxes from SPEX, measured in the 2002/02/20 11:06 flare. The last column shows the means and standard deviations of all 5 imaging methods.

Energy range	Forward flux ratio	Pixon flux ratio	Clean flux ratio	MEM flux ratio	MEM-Vis flux ratio	Average flux ratio
10-12	0.98	0.92	0.90	0.87	0.74	0.88± 0.09
15-17	1.02	1.01	0.99	0.92	0.90	0.97± 0.05
20-22	1.03	1.03	1.04	0.93	0.96	1.00± 0.05
25-29	1.05	1.02	1.08	0.94	0.98	1.01± 0.05
30-34	1.04	1.00	1.04	0.95	0.89	0.99± 0.07
35-39	1.02	1.04	1.06	1.88	0.93	1.19± 0.39
40-50	1.11	1.08	1.16	1.01	1.05	1.08± 0.06
50-60	0.98	0.91	0.99	0.88	0.82	0.92± 0.07
Average	1.03 ± 0.04	1.00 ± 0.06	1.03 ± 0.08	1.05 ± 0.34	0.91 ± 0.10	

given energy range (for instance, spectroscopy uses the off-diagonal spectral-response elements, while the current implementation of imaging uses only the diagonal elements). A first basic photometry test that verifies the consistency of the software is therefore to compare the photon counts of the *SPEX* spectra in different energy ranges with those obtained from images in the same energy ranges. The time profile of the flare, the photon spectrum, the photon count rates and pre-flare background in 8 energy ranges are all shown in §A1 on the CD-ROM. The pre-flare background amounts to a few percent of the peak flux (at energies $\lesssim 40$ keV).

2.2. IMAGE PHOTOMETRY (§A2 ON CD-ROM)

We conduct a photometric test by comparing the photon rates (in units of $photons\ s^{-1}\ cm^{-2}$) integrated over each image with those obtained from the total flux spectra calculated with *SPEX* in identical energy bins and time intervals (for the 2002/02/20, 11:06:00 UT flare). The field-of-view of the images is $64'' \times 64''$ and encompasses the full flare region, centered at the midpoint of the flare brightness distribution. We find that the total fluxes are well conserved in most of the imaging reconstruction algorithms (see ratios in Table 1), they agree with *SPEX* within a few percent for all 5 imaging algorithms (*Forward-fit*, *Pixon*, *Clean*, *MEM*, *MEM-Vis*). The photometric accuracy seems to be uniform in different energy ranges (last column in Table 1). This test essentially verifies that the flux normalization is correctly and consis-

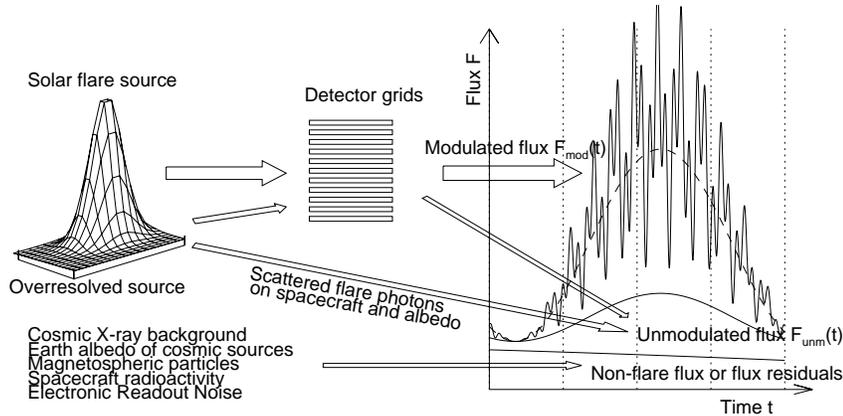


Figure 1. Schematic cartoon of solar and non-solar sources that produce modulated flux $F_{mod}(t)$, unmodulated flux $F_{unm}(t)$, and non-flare sources $F_{back}(t)$ in the time domain of the modulation time profiles. Note that the unmodulated flux is flare-related, because its time variability is proportional to the demodulated flare flux (dashed curve).

tently implemented in the different software modules of each imaging algorithm.

2.3. BACKGROUND COMPONENTS (§A3 ON CD-ROM)

The observed counts consist of at least 3 different components that can be distinguished in the image reconstruction process: (1) modulated flux $F_{mod}(t)$ that is modulated by the rotating grids and originates from resolved flare sources, (2) unmodulated flux $F_{unm}(t)$, which shows no grid modulation but varies proportionally to the incident flare flux, probably produced by scattered flare photons (on the spacecraft and Earth's albedo) or by overresolved sources that are larger than the pitch of the coarsest grid, and (3) non-flare background flux $F_{back}(t)$ that may originate from cosmic X-ray background, magnetospheric particles, Earth albedo of cosmic sources, spacecraft radioactivity, or electronic readout noise (Fig. 1). Background modeling can be performed with the *Pixon* and *Forward-Fit* algorithms. We find an unmodulated flux in the order of $\approx 15\%$ of the flare peak flux, in excess of the preflare background rate ($\approx 1\%$ of flare peak).

2.4. POSITIONAL COMPARISONS (§A4 ON CD-ROM)

Images reconstructed in 4 energy bands with all 5 algorithms are shown in Fig. 2. The source morphology is a simple double footpoint geometry,

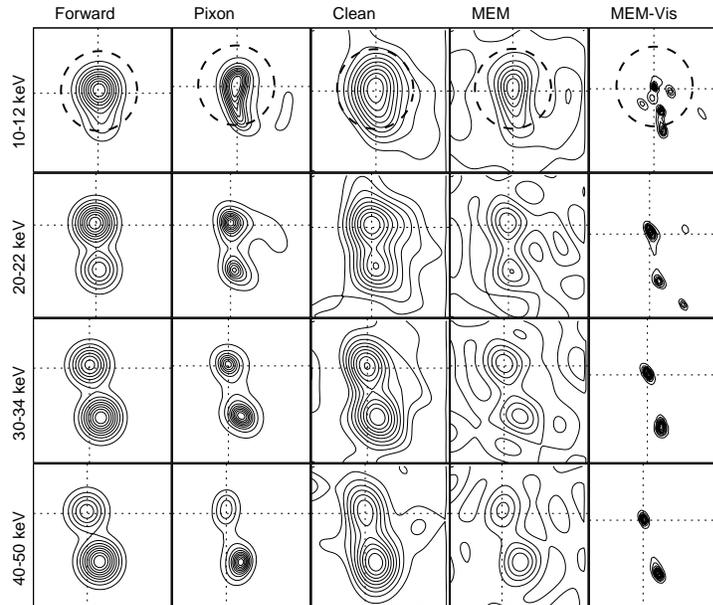


Figure 2. Image comparisons of *Forward-fit*, *Pixon*, *Clean*, *MEM*, and *MEM-Vis* images reconstructed in 4 energy bins. The contour levels are at 10%, 20%, ..., 90% of the maximum flux. The location of the northern flux maximum is indicated with a dotted cross-hair. The dotted circle has a radius of $18''$, which is used for halo/core flux ratio measurements.

which is consistently reproduced by all 5 algorithms. *MEM-Vis* in its current implementation does not take corrections for time variability into account, and thus seems to have a compromised image quality for this case (integrated over a time interval of 40 s). We measure the centroid location (x_N, y_N) of the northern flare source with sub-pixel accuracy by parabolic interpolation at the source peak. Averaging these source positions among the different image algorithms we find a standard deviation in the order of 0.5 pixels (with pixel size of $1''$), which is close to the accuracy expected from simulations for the corresponding count rates. Only *MEM-Vis* shows occasionally larger deviations, very likely to be a side-effect of the compromised image quality.

2.5. AMPLITUDE AND WIDTH COMPARISONS (§A5 ON CD-ROM)

The reconstructed source widths w vary to a larger degree between individual imaging algorithms. We define the width w of a source by the rectangular equivalent width of a flux cross-section profile across the source peak, i.e., the integral of the flux profile divided by the

peak flux. Compared with the spatial resolution of the finest used grid ($w_{res} \approx 11.8''$ for grid#4), we find that the width ratio of the reconstructed nonthermal sources at 25 keV is $w/w_{res} = 1.2$ for *Forward-Fit*, $w/w_{res} = 0.7$ for *Pixon*, $w/w_{res} = 1.7$ for *Clean*, $w/w_{res} = 3.3$ for *MEM*, and $w/w_{res} = 0.2$ for *MEM-Vis*. The *Pixon* and *Forward-Fit* algorithms yield compatible widths, while those from *MEM* are significantly larger, and those from *MEM-Vis* are systematically narrower (probably a side-effect of compromised image quality for time-variable sources). The larger widths obtained from *Clean* maps result from the convolution with the *Clean* beam, but they agree when the *Clean* maps are deconvolved with the beam. Apparently, *MEM* does not converge to the best solution when there are too many degrees of freedom.

Because the flux per feature ($F \approx aw^2$) is well-conserved, the peak flux amplitude a of an image map is roughly reciprocal to the square of the source widths, i.e., $a \propto 1/w^2$. Because of this strong sensitivity to the reconstructed source width, it is not unusual that the peak flux differs up to an order of magnitude between different image algorithms, depending on the convergence behavior of the reconstruction algorithm. For imaging spectroscopy, therefore, it is important to sum over an entire feature (such as a flare footpoint) rather than to examine the flux of a source on a pixel by pixel basis.

What is the best method for determining source sizes? Tests with a flare that consists of a simple compact source are presented in Section B1 on the CD-ROM, for the 2002-Mar-18, 19:15 UT flare. Forward-fit, Pixon, and MEM yield a source size between 13.1'' and 14.6'' in the energy range of 10-12 keV. Schmahl & Hurford (2003) used the method of *relative amplitudes* and find a somewhat smaller size of 11''. If the sources are simple (gaussian-like), the method of relative amplitudes is likely to be more reliable than the imaging methods. When the sources are elongated or elliptical, Pixon and Forward-fit are probably more reliable. Sources reconstructed with Clean need to be deconvolved with the point-spread function of the used grids. When the sources are very weak or if the source size is so small ($\lesssim 3''$), so that the in-phase superposition of modulation amplitudes does not exceed the Poisson fluctuations, the determination of source size is ambiguous with every algorithm because of the indifference in the significance test.

2.6. HALO/CORE FLUX RATIOS (§A6 ON CD-ROM)

We measure the flux ratio between a *core* (C) region (inside a radius of 1.5 times the resolution of the finest subcollimator used in the map) and the outer *halo* (H) region. This H/C flux ratio reflects how many photons are spread in the image outside the compact source component. It

is found to be low for *Forward-fit*, *Pixon*, and *Mem-Vis*, in the order of a few percent, while *Clean* shows a somewhat larger ratio of $H/C \lesssim 30\%$ due to the convolution with the clean beam and the addition of clean residuals. *MEM* exhibits a large noise ratio of $H/C \lesssim 160\%$, a clear indication that the image algorithm does not converge properly in some cases, in particular for small pixel sizes ($1''$) and large field-of-views, which corresponds to a larger degree of freedom in the image reconstruction.

2.7. SPATIALLY RESOLVED SPECTRA (§A7 ON CD-ROM)

We fit a two-component spectrum (with an exponential function for the thermal component and a powerlaw function for the non-thermal component) to the image fluxes obtained in 8 different energy channels. Comparisons of the best-fit parameters with those obtained with the spectral fitting software SPEX show agreement between the non-thermal fluxes and power-law slopes within a few percents for all imaging algorithms. However, we emphasize that spatially-resolved spectra should only be extracted from images by integrating over an entire source structure (or image feature), never from single pixels (because of the amplitude-width uncertainty, see §2.5).

2.8. GRID SELECTION (§A8 ON CD-ROM)

The grid selection determines the width of the reconstructed sources in the case of unresolved sources. We found that the reconstructed source width indeed scales (within a factor of 2) with the spatial resolution of the finest used grid for most of the image algorithms (except for *MEM-Vis*, which super-resolves, and for *MEM*, which under-resolves the sources).

2.9. PIXEL-SIZE COMPARISONS (§A9 ON CD-ROM)

The image reconstruction should provide a solution that is independent of the map parameterization, such as the field-of-view or pixel size, provided that the sources are resolved. Only in the case of unresolved sources, the reproduced source width represents an upper limit specified by the pixel size. We reconstruct the images with pixel sizes of $1''$, $2''$, and $4''$ and find indeed an invariant solution for 4 algorithms, with a width that is related to the resolution of the finest used grid. Only *MEM-VIS* shows a different behavior, yielding a source size that scales with the pixel size rather than with the resolution of the finest used grid.

2.10. FIELD-OF-VIEW COMPARISONS (§A10 ON CD-ROM)

The selected field-of-view is found not to affect the quality of the image reconstruction for *Forward-fit*, *Pixon*, and *Clean*. For *MEM* and *MEM-Vis*, the quality of the image reconstruction seems to improve for minimal field-of-views that closely encompass the sources, apparently because this minimizes the number of degrees of freedom in the image reconstruction.

2.11. TIME INTERVAL COMPARISONS (§A11 ON CD-ROM)

Since the time interval is proportional to the number of photons used in the image reconstruction, the quality and signal-to-noise ratio is expected to improve for longer time intervals. We find that the signal-to-noise ratio indeed improves with longer time intervals for *Pixon*, *Clean*, and *MEM-Vis*. *Forward-fit* is a parametric model, where a better signal-to-noise ratio translates into smaller uncertainties of the best-fit model parameters. For *MEM* we find no noise-to-signal improvement with longer time intervals for images with small pixel sizes or large field-of-views, which probably indicates a convergence failure for those cases.

3. CONCLUSIONS

This study demonstrates that most available *RHESSI* image algorithms have a reasonable photometric accuracy for the total flux contained in the images, but differ substantially in the geometry of the reconstructed sources. The results can be summarized as follows: Three algorithms (*Forward-Fit*, *Pixon*, *Clean*) converge to the best solution within the constraints of the spatial resolution of the finest used grids, within the expected uncertainty of the signal-to-noise dictated by photon statistics. The current implementation of the *MEM* algorithm does not converge well for cases with a large number of degrees of freedom (for small pixel sizes and large field-of-views). The current version of *MEM-Vis* does not correct for time variability and thus yields a compromised image quality for long-duration time intervals. Nevertheless, the user can produce consistent and high-quality images with the *MEM* and *MEM-Vis* algorithms by exercising a careful choice of image parameters. Spectroscopic flux comparisons should always be done for image parts that encompass entire features or source components, rather than on a pixel by pixel basis.

This study entails image comparisons considering the most basic parameters, but ignores a number of other effects that are left to future

studies, such as: (1) the role of the “halo component”, which was found to extend out to 2-3 times the radii of the core sources and contains up to 25% of the total flux (Schmahl & Hurford, 2003), (2) the neglect of the correct off-axis distance for spectroscopy, (3) the use of different time-binnings, or (4) pulse pile-up corrections and attenuator effects in intense flares.

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